Lecture Plan					
M.Tech (EI) Semester 2nd			Code E16I 604		
Subject N			No. of Credits 4		
Unit	Торіс	Duration (hours)	References		
1	Optimal Control System ,Performance Indices,		"Control Systems "by Nagrath		
	Formulation of Optimization Problems	2	& Gopal , "Modern Control System" by K.Ogata		
	Time Optimal Control Systems, Characterstics of a Plant, Minimisation of Functions, Numerical problems	2	"Control Systems "by Nagrath & Gopal , "Modern Control System" by K.Ogata		
2	Linear dependence of vectors, complete state	2	"Control Systems "by Nagrath		
	controllability of continuous time systems, Numerical problems	2	& Gopal , "Modern Control System" by K.Ogata		
	Complete state controllability of discrete time systems, Z-transform, Inverse Z-transform, Numerical problems	4	"Control Systems "by Nagrath & Gopal , "Modern Control System" by K.Ogata		
	Alternate form of complete state controllability, output controllability	2	"Modern Control System" by K.Ogata		
3	Complete state observability of continuous time systems, Numerical problems	2	"Control Systems "by Nagrath & Gopal , "Modern Control System" by K.Ogata		
	Complete state observability of discrete time systems, Numerical problems	2	"Control Systems "by Nagrath & Gopal , " digital Control Systems" by M.Gopal		
	Alternate form of complete state observability, Principle of duality, Numerical problems	2	"Modern Control System" by K.Ogata		
4	Time optimal control for continuous time systems with bounded control signals, continuous time linear state regulator Numerical problems,	3	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Time optimal control for discrete time systems, discrete time linear state regulator, Numerical problems	3	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Optimal control system based on quadratic performance indices, Calculus of variations	4	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Application of optimal control to dynamic systems, Numerical problems	2	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Pontryagin Minimum Principle & its applications to optimal control problems with constraints, Numerical problems	3	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Dynamic Programming , Bellman-Jacobi equation& its applications to optimal control problems, Numerical problems	4	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Optimal control system for distributed parameter system, Solution of algebraic Ricattii's equation for linear regulator problem	3	"Optimal Control Theory" by A.J.Kirk, "Modern Control System" by M.Gopal		
	Total	40	, , ,		